

DEPLOYMENT LOG for IceCube STRING # 57

Deployment Start: at 6.55 am on 1/20/07

Deployment End: at 6:46pm on 1/20/07

Target depth (DOM60): 2450 m Final depth: 2452.3

Deployment Crew

AURA

		A STATE OF THE STA
Position	First Shift	Second Shift
Shift lead	Tom Ham	Tom Ham, A. Karle
DOM install 1 (high)	Jim Latshaw	Ken Ratzlaff
DOM install 2 (low)	Rod Matfison	Hazar Landsman
DOM supply 1 / DOM install 3	Sven Lidstron	-Darryn Blythe
DOM supply 2 / floater	bary Sulliva	Keith Beattie.
Winch operator (cable & tower)		
Notary (logbook & photos)	7 Justin Vandenbrouck	J. Vandy bravile
PTS (monitoring / sensors))	
Support (optional) Bubble Cam	Michelanylo D'Agostino	m. D: Agastino

Time of shift change:

Summary/Comments:

Day "The Machine" Shift

2245 - 2295



Hole Handover
maximum drift in x: □ plot
maximum drift in y: plot
maximum depth: 2480 m
□minimum radius: <u>Mom</u> □ plot
□ plot of predicted radius vs depth and time
Hole dimensions verified Time: 4:394m
Drill Lead:
name / signature / date
Deployment Lead: 10m Han Joseph 1/9/07 name / signature / date
□ Handover complete

	Hole Logging (skip if not applicable	
□ Logger drop started□ Logging started□ Logging ended		Spec Bubbll
☐ Estimated hole lifetime Must reach targ		Hedlo



IceCube String Deployment Log String 57
4:35 am: hot water flow stopped last night

Deployment Startup				
Ø €- stops tested	Time: 6:55am			
 ☐ Cable winch anchored and operational ☐ Tower winch operational ☐ Tie off verified ☐ Yellow rope verified 				
Deployment monitoring system (PTS) operational DDB# oy Pressure sensors on hand: Paro and Keller, with backups Laser ranger, tape measure (metric) on hand				
Bleeder string installed (on quad connectors inside cable reel drum)				
Uphole pressure system on hand: Setra sensor and c	cable_			
DOMs placed in racks Weight stack on hand: weights (5) and 2 m cable 7 17 m string extension steel cable on hand				
Safety checks complete (□ 1 st shift □ 2 nd shift) ☐ Crew safety briefing ☐ E-stop locations identified ☐ TOS evacuation procedures reviewed ☐ Mustering point identified ☐ Snow mobile driver(s):				
CPR trained: Tom Swn Jim	Dart			
Food runners:	call galley at 65521			
End of Main Cable brought into TOS and secured	*			

The state of the s	Cable er	nd attachn	nents	a a	
	AN	se above			
□ Weights (5) attached □	1				**
	ed (weight	stack comp	lete)	Time: ½7:15	_=
- tomection	n of	Bubble	Cam		3/37



*

IceCube String Deployment Log String 57
Bubble Cam affachment wast very well thanks to

Photos: DOM ids (风long ⋈ short); connectors (□ long □ short)
DOM position 60 excellent work of M. DOM id: TP GP1227 (T, Long) D'Agos fino. BC was connected directly to readout before winch placed + cable brought in. 15 min. video recorded inc. R
winch placed + cable brought in. 15 min. video recorded inc. R
Bottom shackle connected to weight stack Payout: (17 m en 510)
☐ Top shackle connected to 17 m steel cable
Photos: Whole view Long delay moving winch into place, Photos: Whole view Long delay moving winch into place, OM position 59 (U, Short) Cable mark: DOM id: UP 5 H0200 (U, Short) Cable mark: Stadion Of Rotton shackle connected to 17 m cable
getting it operational. B
DOM position 59 DOM id: UP <u>5 H 0 2 0 0</u>
(U, Short) Cable mark:
Bottom shackle connected to 17 m cable
Dottom shackie connected to 17 in capie
Main cable and taned to 17 m steel cable (use laser ranger)
Photos: If phi orientation I whole view
motos. I pin orientation at whole view
Breakout 30 & Shift bead Ham's Breakout 30 Respectively bead Ham's Breakout 30 Respectively bead Ham's Breakout 30 Respectively bead Ham's
VIAT ()(1.3)
observed floating on water surface. Depth:
- LongDOM will be recorded by Bubble cam. Payout
Connector O-ring in place and I lubed (1 6 Pack) x (8 observers)
☐ breakout O-ring in place and ☐ lubed
⊠ connected
- ShortDOM
✓ connector O-ring in place and ✓ lubed
☐ breakout O-ring in place and ☐ lubed
connected
∠ Loose pigtails taped to cable
Paro Serial #: 104 660 Nipple non □ off Connected Noperational Air pressure [PSI]: 9.47 □ Cable mark: NN Distance to DOM59: 1.46+17.4
☐ Cable mark: NK Distance to DOM59: 1. 46+17.4
= 18.9
All clear to lower cable ⊚



Photos: DOM ids (☐ long ☐ short); connectors (☐ long ☐ short)		
DOM position 58		DOM id: TP_
(T, Long)	Cable mark: 1 /3	
Bottom shackle of Top clutch conner Bow OK → If cl Photos: A phi orien	ected at link #_19	Δ(58-59): <u>/6.</u> ງ
DOM position 57		DOM id: UP 5 H 0130
(U, Short)	Cable rk: 29	
Bottom shackle of Top clutch complete Breakon Connecte	ad abed	Δ(57-58): 16 9 Time: Now 9:31 Last b/o Δt [min] Depth: Paro 9-79
- ShortDOM in connector O-1	ring in place and □ lubed ng in place and □ lubed.	710 96 load
△ Loose pigtails tap	ped to cable	
	☐ All clear to lower cabl	e 😊



Photos: DOM ide (M long □ sho	rt): connec	tors (lon	σ □ short)
Photos: DOM ids (★ long □ short); connectors (□ long □ short)				
DOM position 56	Coble	111	D	OM id: TP 6 7 4281
(T, Long)	Cable mark:	46.5		
☐ Bottom shackle of Top clutch connection Bow OK → ⚠ c. Photos: ☒ phi orier	ected at link # lutch zip tied		Δ(56-	57): <u>16.9</u>
DOM position 55			D	OM id. IIP 5 11 07.74
(U, Short)	Cable mark:	63.5		OM id: UP 5 4 02 26
Bottom shackle of Top clutch connection Bow OK → □ clutch crient	connected ected at link # lutch zip tied	19	Δ(55-	56): <u>6.9</u>
Breakout 28		Δ.	8	Time:
- LongDOM connector O- breakout O-r connected - ShortDOM connector O- breakout O-r connected Loose pigtails tar	ring in place a	nd □ lubed and □ lube nd □ lubed	d Δt	Now 9: 39 ast b/o [min] Depth: Paro 97 Payout - 12
Loose pigtails tap	ped to cable	59	? ~-4 ? &~.	
		60	€~.	-21
2 '	All clear	to lower	cable 😊	



Photos: DOM ids (long □ short); connectors (l	☐ long ☐ short)
DOM position 54	DOM id: TP 5 HOZZI
(T, Long) Cable mark: 80	
Bottom shackle connected Top clutch connected at link # Bow OK → ✓ clutch zip tied Photos: ✓ phi orientation ✓ whole view	Desagari
DOM position 53 (U, Short) Cable mark: 97	
Bottom shackle connected ☐ Top clutch connected at link # Bow OK → clutch zip tied Photos: phi orientation whole view	
Breakout 27	Time:
- LongDOM connector O-ring in place and □ lubed breakout O-ring in place and □ lubed connected	Now 9:45 Last b/o Δt [min] Depth: Paro (29.20 Payout -92
- ShortDOM connector O-ring in place and □ lubed breakout O-ring in place and □ lubed connected	775 load
A Loose pigtails taped to cable	
All clear to lower cable	©



Photos: DOM ids (Nong / short); connectors	$(\Box \text{ long } \Box \text{ short})$
DOM position 52		DOM id: TR
(T, Long)	Cable mark: 114,5	674477
Bow OK → ∠ c	ected at link # 19	Δ(52-53): 16. 9
DOM position 51 (U, Short)	Cable mark: 13 \	DOM id: UP 5HOZIZ
\square Bow OK $\rightarrow \square$ c	ected at link #	Δ(51-52): [6-9
Breakout 26		Time:
 breakout O-1 connected ShortDOM connector O-1 	ring in place and □ lubed ing in place and □ lubed ring in place and □ lubed ring in place and □ lubed uped to cable	Now 9:53 Last b/o Δt [min] Depth: Paro 163.30 Payout - 120.2
0		
8	All clear to lower cab	le 😡



Photos: DOM ids	(X long short); connector	rs (long short)
AND SHOW SHOW SHOWING SAMES		
DOM position 50		DOM id: 74 5 H0217
(T, Long)	Cable mark: 14	AP
■ Bottom shackle	connected	
The second secon	nected at link # 19	Δ(50-51): 16-9
Bow OK → 🖈	The state of the s	
Photos: 🏿 phi orie	entation 🗷 whole view	
Curved distance		Vertical distance:
5 6	later	,
DOM position 49		DOM id: UP 5 H 0 1 8 2
(U, Short)	Cable mark: 65	
Dottom also alsla		
Bottom shackle	nected at link # (9	Δ(49-50): (6-9
Bow OK → 🗷		Δ(49-50):
Photos: A phi orie	entation 🗷 whole view	
- Curved distance		Vertical distance:
		vertical distance.
Breakout 25		Time:
5 Z g		Now 10:02
- LongDOM	* ⁵	Last b/o
	oring in place and □ lubed	Δt [min]
- breakout O-	ring in place and lubed	Depth:
		Paro (98
		Payout
- ShortDOM		
39	\Box -ring in place and \Box lubed	840 load
V	ring in place and □ lubed—	, to xound
connected		
	12. 11.	
	aped to cable	
III		



Photos: DOM ids (long /short); connector	rs (long short)
DOM position 48		DOM id: TP 6 Y 4309
(T, Long)	Cable mark: 182	
Bow OK → Ø cl	ected at link #_19	Δ(48-49):(6 . 9
DOM position 47 (U, Short)	Cable mark: (99	DOM id: UP 6 H 7512
Bow OK → the	ected at link # 19	Δ(47-48): <u> 6.9</u>
Breakout 24		Time:
□ breakout O-r	ring in place and □ lubed ing in place and □ lubed	Now (0: 11 Last b/o Δt [min] Depth: Paro 232 Payout 92.5
	ring in place and □ lubed ing in place and □ lubed	913 Page
Loose pigtails tap	ped to cable	*
		8
	All clear to lower ca	ble ☺



parate pro		W.	
Photos: DOM ids (☒ long ☒ short); connectors (☐ long ☐ short)			
DOM position 46	•	DOM id: TP5 # 0205	
(T, Long)	Cable mark: 216		
 	ected at link # <u>(9</u>	Δ(46-47): 16. 9	
DOM position 45		DOM id: UP 5 40208	
(U, Short)	Cable mark: 233	DOM Id. 01 5 40 22 0	
ß Bow OK → ズ cl	ected at link #() utch zip tied	Δ(45-46): 16.9 added 18.9 (was g) s Δ(00 Mb) - Paro) Time:	
20		Now_ 10:18	
	ring in place and □ lubed ing in place and □ lubed —	Last b/o Δt [min] Paro 285, 32 Payout - 205.66	
(ring in place and □ lubeding in place and □ lubed	884 load	
Loose pigtails tap	ped to cable		
		* * * * * * * * * * * * * * * * * * *	
	☐ All clear to lower cab	(e)	



		8
Photos: DOM ids (☼ long ⅓ short); connectors (□ long □ short)		
DOM position 44		DOM id: TP 6 Y 42 43
(T, Long)	Cable mark: 250	
Bottom shackle co Top clutch connect Bow OK → Clut Photos: phi orienta	ted at link # <u>(9</u> tch zip tied	Δ(44-45): <u>[6.8</u>
DOM position 43 (U, Short)	Cable mark: 26 6	DOM id: UP 5 H 0 2 46
☐ Bottom shackle co☐ Top clutch connect Bow OK → ☐ clutch connect Bow OK → ☐ clutch Photos: ☐ phi orienta	ted at link #t \tch zip tied	Δ(43-44): [6.9]
Breakout 22		Time:
□ breakout O-ring□ connected- ShortDOM	ng in place and □ lubed g in place and □ lubed ng in place and □ lubed	Now (0:26 Last b/o Δt [min] Depth: Paro 319-6 Payout - 92.51?
	g in place and [] lubed	
Loose pigtails tape	d to cable	*
	All clear to lower cable	e 😊



Photos: DOM ids (M long M short): connectors (long short)		
Photos: DOM ids (\(\times\) long \(\times\) short); connectors (\(\su\) long \(\su\) short)		
DOM position 42 (T, Long) Cable mark: レッソ	DOM id: TP540153	
(1, Long) Cable mark.		
Bottom shackle connected	17.0	
☐ Row OK → ☐ clutch zip tied	Δ(42-43): 17.0	
 ✓ Bow OK → Ø clutch zip tied Photos: Ø phi orientation Ø whole view 		
DOM position 41	DOM id: UP 5 HOIS 2	
(U, Short) Cable mark: 3 00		
★ Bottom shackle connected		
☐ Top clutch connected at link # (9	Δ(41-42): \(\begin{aligned}	
Bow OK → Clutch zip tied		
Photos: A phi orientation A whole view		
Breakout 21	Time:	
Dieakout Zi		
T - POM	Now_10:35	
- LongDOM	Last b/o	
☒ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed	Δt [min] Depth:	
☐ connected	Paro 354	
L and the second	Payout 26 4	
- ShortDOM		
☐ breakout O-ring in place and ☐ lubed ☐ connected		
KI Connected	2	
Loose pigtails taped to cable		
9		
ж		
All clear to lower ca	able ©	



Photos: DOM ids (long short); connectors	$(\Box \text{ long } \Box \text{ short})$	
DOM position 40	DOM id: TP 6 Y 4 2 3 7	
(T, Long) Cable mark: 3 1 8		
 ☐ Bottom shackle connected ☐ Top clutch connected at link #	Δ(40-41): 16-9	
DOM position 39 (U, Short) Cable mark: 334	DOM id: UP 5 H 0126	
Bottom shackle connected Top clutch connected at link # Bow OK → clutch zip tied Photos: The phi orientation whole view	Δ(39-40): <u>16. 9</u>	
Breakout 20	Time:	
- LongDOM	Now 10 = 4 3 Last b/o Δt [min] Depth: Paro 390 Payout -293	
 ShortDOM 		
Loose pigtails taped to cable		
5 B M		
ՃAll clear to lower cable ⊚		





Photos: DOM ids (long short); connectors	(□ long □ short)
DOM position 36 38	DOM id: TP 6 54 01 0
(T, Long) Cable mark: 352	
 ✓ Bottom shackle connected ✓ Top clutch connected at link # ✓ Bow OK → Ø clutch zip tied Photos: Ø phi orientation © whole view 	Δ(36-37):
DOM position 35 37 (U, Short) Cable mark: 368	DOM id: UP 540194
Bottom shackle connected ☐ Top clutch connected at link #(☐ ☐ Bow OK → ☐ clutch zip tied ☐ Photos: ☐ phi orientation ☐ whole view	Δ(35-36): [[] 6. 9
Breakout 18 19	Time:
 LongDOM ✓ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed ✓ connected ShortDOM ✓ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed ⋈ connected 	Now 10-50 Last b/o Δt [min] Depth: Paro 424 Payout — 324
M Loose pigtails taped to cable	
Put two Kellers (one is for backup) in bucke	t of water/ice mix
e z	
	ole 😊



Photos: DOM ids (ଢ long ☒ short); connectors (☐ long ☐ short)		
DOM position 3436	DOM id: TP 6 Y 4421	
(T, Long) Cable mark: 3 85		
Bottom shackle connected Top clutch connected at link # 1 9 Bow OK → A clutch zip tied Photos: Phi orientation > whole view	Δ(34-35): [5 16.9]	
DOM position 33 35 (U, Short) Cable mark: 401.5	DOM id: UP5H0114	
Pottom shookle connected		
 Bottom shackle connected ∑ Top clutch connected at link # 19	Δ(33-34):	
Photos: 🕅 phi orientation 🖄 whole view	9	
Breakout 17 18	Time:	
	Now_10:57	
- LongDOM	Last b/o	
	Δt [min]	
☐ breakout O-ring in place and ☐ lubed	Depth:	
connected	Paro 474	
	Payout - 370	
- ShortDOM		
☐ breakout O-ring in place and ☐ lubed		
A connected	¥ d	
∠ Loose pigtails taped to cable		
☑ All clear to lower ca	ble 🐵	



Photos: DOM ida	I lang [] short); connectors	(Inna I short)
	d long	Cu long is short)
DOM position 32	5 D A A A A A A A A A A A A A A A A A A	DOM id: TP_679251
(T, Long)	Cable mark: 4/9	
\boxtimes Bow OK $\rightarrow \boxtimes$ cl	ected at link # 19	Δ(32-33):
DOM position 31	32 3 3	DOM id: UP 6P1262
(U, Short)	Cable mark: 436	BOW Id. OI GFILDE
(U, Short)	Cable Hark. 7 3 8	
Bow OK → Photos: phi orien	ected at link #(Δ(31-32): 6 9
31:	broken convitor	2
Breakout 1/6	tand	Time:
	na photo	Now 11:04
- LongDOM	No 1	Last b/o
<u> </u>	ring in place and □ lubed	Δt [min]
	ing in place and □ lubed	Depth:
connected		Paro 491.6
7 7 8 9 87 8 9 8 8		Payout - 387,98
- ShortDOM		
A connector O-	ring in place and □ lubed	
	ing in place and □ lubed	1130 load
	a a	x dad
		s - E
📈 Loose pigtails tap	ped to cable	
	s v =	
2 0	5 18	
- <u>- 2</u>		
5	- All I (I	
	📈 All clear to lower cab	DIE 😊



Photos: DOM ids (ばlong □ short); connectors (□ long □ short)		
DOM position 38 32	DOM id: TP 69147 2	
(T, Long) Cable mark: 45 3	,	
 ☑ Bottom shackle connected ☑ Top clutch connected at link #	Δ(38-39): 16·9	
DOM position 37 3\ (U, Short) Cable mark: 476	DOM id: UP674232	
Bottom shackle connected Top clutch connected at link #	Δ(37-38): <u>16 9</u>	
Breakout 19	Time:	
- LongDOM	Now 11:17 Last b/ο Δt [min] Depth: Paro 5 28 Payout -420	
- ShortDOM	and the state of t	
△ Loose pigtails taped to cable		
□ All clear to lower cable	e ⊚	



Photos: DOM ids (☐ long ☐ short); connectors	s (□ long □ short)	
DOM position 30	DOM id: TP 67877	
(T, Long) Cable mark: 69 663	189487 674349	
Bottom shackle connected ☐ Top clutch connected at link # ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐ ☐	Δ(30-31):(6.9	
DOM position 29 (U, Short) Cable mark: 504	DOM id: UP 6 7 4 4 2 4	
 ☐ Bow OK → ☐ clutch zip tied Photos: ☐ phi orientation ☐ whole view 	Δ(29-30):	
Breakout 1500 5	Time:	
- LongDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	Now 11: 26 Last b/o Δt [min] Depth: Paro Payout	
- ShortDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected		
☐ Loose pigtails taped to cable		
Thermistor Present Distance to DOM Keller Connected Doperational Connected Doperational Connected Distance to Domester Domester Distance to Domester Dom	The state of the s	
All clear to lower cable ⊚		



Photog. DOM ida (14 long short), garnactora (long short)		
Photos: DOM ids (♣ long ☐ short); connectors (☐ long ☐ short)		
DOM position 28	DOM id: TP 6 Y446	
(T, Long) Cable mark: 5		
 ☑ Bottom shackle connected ☑ Top clutch connected at link #? ☑ Bow OK → Ø clutch zip tied Photos: □ phi orientation Ø whole vie 		
DOM position 27 (U, Short) Cable mark: 5	DOM id: UP 6 Y 294	
Bottom shackle connected ☐ Top clutch connected at link # ☐ Bow OK → ☐ clutch zip tied Photos: ☐ phi orientation ☐ whole vie		
Breakout 14	Time:	
 LongDOM Connector O-ring in place and □ breakout O-ring in place and □ connected ShortDOM Connector O-ring in place and □ breakout O-ring in place and □ Connected 	ubed Paro Paro S-98 Keller Payout -478 lubed ubed	
Loose pigtails taped to cable	lunch brank	
☑ All clear to lov	wer cable ☺	



ACTION OF THE PROPERTY OF THE		
Photos: DOM ids (风 long □ short); connectors (□ long □ short)		
DOM position 26		DOM id: TP 6 th 75.15
(T, Long)	Cable mark: 554.5	
Bow OK →X cl	ected at link #	Δ(26-27): 16.9
DOM position 25		DOM id: UP 6 7 4 3 9 6
(U, Short)	Cable mark: 5 71.5	2011 Id. 01 41 7 276
Bottom shackle of Top clutch connection Bow OK → In clutch	ected at link #lutch zip tied	Δ(25-26): 16.5
Photos: 🕅 phi orier	ntation / whole view	
Breakout 13		Time:
v *	2 1	Now_1:02
- LongDOM		Last b/o
_	ring in place and □ lubed	Δt [min]
☐ breakout O-r	ing in place and \Box lubed	Depth:
connected connected		Paro 6 30.18
· ·		Keller _ 36588
- ShortDOM		Payoutsos
	ring in place and □ lubed	
	ing in place and \square lubed	
connected		
A T	1. 11	
Loose pigtails ta	ped to cable	
,		
`		
F. A. G		•
□ All clear to lower cable ⊚		



Photos: DOM ids (♥ long □ short); connectors (□ long □ short)		
DOM position 24	DOM id: TP5 HO103	
(T, Long) Cable mark: 579	N	
☐ Bottom shackle connected ☐ Top clutch connected at link # 1 9 ☐ Bow OK → ★ clutch zip tied ☐ Photos: ☐ phi orientation ★ whole view	Δ(24-25): 7.0	
DOM position 23	DOM id: UP6P1206	
(U, Short) Cable mark: 0605	* ************************************	
Bottom shackle connected Top clutch connected at link # Bow OK → M clutch zip tied Photos: M phi orientation M whole view	Δ(23-24): 17.0	
Breakout 12	Time:	
- LongDOM	Now_ /: / 1 Last b/o	
	Δt [min]	
□ breakout O-ring in place and □ lubed	Depth:	
★ connected	Keller 98	
- ShortDOM	Payout ~532	
 ✓ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed ✓ connected 		
Loose pigtails taped to cable		
*		
M All clear to lower can		



Photos: DOM ids (Nang Webert): connectors	s (long long short)
Photos: DOM ids (long short); connectors	
DOM position 22	DOM id: TP 5H 0129
(T, Long) Cable mark: 6 23	
 Bottom shackle connected Top clutch connected at link # / 9 Bow OK → ⋈ clutch zip tied Photos: ⋈ phi orientation ₭ whole view 	Δ(22-23): 16.9
DOM position 21	DOM id: UP 6 74416
(U, Short) Cable mark: 63 9	BOW Id. OI
(0, Short) Cable mark.	
☑ Bottom shackle connected	
Top clutch connected at link # (9	Δ(21-22): 17.0
 Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view 	
Photos: phi orientation whole view	
Breakout 11	Time:
	Now_ 1:17
- LongDOM	Last b/o
	Δt [min]
☐ breakout O-ring in place and ☐ lubed	Depth:
X connected	Paro 69 8
	Keller 232
- ShortDOM	Payout558
breakout O-ring in place and □ lubed	
🕅 Loose pigtails taped to cable	
*	
2	
	ole 😊



Photos: DOM ids (M long N short): connectors (long short)		
Photos: DOM ids (☐ long ☐ short); connectors (☐ long ☐ short)		
DOM position 20	DOM id: TP 6 14271	
(T, Long) Cable mark: 656		
☐ Top clutch connected at link # 19	Δ(20-21): [7.0]	
Bow OK → M clutch zip tied	_(
Photos: phi orientation 🗷 whole view		
Curved distance around DOM:	Vertical distance:	
	-	
DOM position 19	DOM id: UP <u>67428</u> 4	
(U, Short) Cable mark: 6 7 3-5		
D though all a consected		
Bottom shackle connected	A(10.20), 17.A	
Top clutch connected at link #_ @ 19 Bow OK → M clutch zip tied	Δ(19-20): 17-0	
Photos: phi orientation whole view		
# Curved distance around DOM:	Vertical distance:	
B Curved distance around DOM	vertical distance.	
Breakout 10	Time:	
	Now_1:24	
- LongDOM	Last b/o	
☐ connector O-ring in place and ☐ lubed	Δt [min]	
☐ breakout O-ring in place and ☐ lubed	Depth:	
connected	Paro 7 33.14 Keller 7 33.24	
Fixed off	8 ← Keller 7 33.24	
- ShortDOM	Payout > 84	
	TE	
☐ breakout O-ring in place and ☐ lubed		
Loose pigtails taped to cable		
*		
	¥,	
🗡 All clear to lower ca	ble 😊	



Photos: DOM ids	(X long X short); connectors	(□ long □ short)
DOM position 18		DOM id: TP @ 5 HO 185
(T, Long)	Cable mark: 6 90	201111111111111111111111111111111111111
(1, E0119)	odbio mark. 6 / 5	
Bottom shackle	connected	
	nected at link #(9	Δ(18-19): 16.9
Bow OK →	clutch zin tied	_(.55)
	entation whole view	
Thomas Prince	Alterior A Williams	
DOM position 17	•	DOM id: UP 644422
(U, Short)	Cable mark: 707	DOWN IG. OI VITTE
(0, 511011)	Cable Hark.	
Bottom shackle	connected	
/ V	nected at link # (9	Δ(17-18): (7,0
\nearrow Bow OK $\rightarrow \nearrow$		
Photos: A phi orie	entation 🕅 whole view	
riotos. A bin orio	1. 10 m = line I a	it line up
Breakout 9	hite markings do	Time
Dreakout 3	Se proto	Time:
		Now 1: 32
- LongDOM		Last b/o
connector C	oring in place and □ lubed	Δt [min]
	ring in place and □ lubed	Depth:
x connected	<u> </u>	Paro 767
	w.	Keller 768
- ShortDOM		Payout - 609
	oring in place and □ lubed	14,041
	ring in place and □ lubed	
⊠ connected	ing in place and - labed	
A connected		1159 load
No I ooga niotaila t	aned to cable	Long
Loose pigtails t	aped to capie	
e		
Wa at a second		
	□ All clear to lower cabl	le ⊎



	E	
Photos: DOM ids (X	long short); connectors	(□ long □ short)
DOM position 16		DOM id: TP 6 Y4 377
(T, Long)	Cable mark: 4724	
 M Bottom shackle co M Top clutch connect M Bow OK → M clutch Photos: M phi orienta 	ted at link # <u>(9</u> tch zip tied	Δ(16-17): \ \ 6.9
DOM position 15		DOM id: UP 6 Y 44 82
N.E. Carrier	Cable mark: 741	
M Pottom chookle oo	nnatad	
☒ Bottom shackle co☒ Top clutch connec☒ Bow OK → ☒ clu	ted at link #[9	Δ(15-16): (6, 9
Photos: phi orienta		9
, , , , , , , , , , , , , , , , , , , ,		
Breakout 8	¥ ·	Time:
□ breakout O-rin⋈ connectedShortDOM⋈ connector O-ri	ng in place and □ lubed g in place and □ lubed ng in place and □ lubed g in place and □ lubed	Now 1'4 Last b/o Δt [min] Depth: Paro 80 2 Keller 80 1 Payout - 6 35
∠ Loose pigtails tape	ed to cable	
		s. 10
		y v
a x		e " La la
	☑ All clear to lower cab	le 😡



	a ²
Photos: DOM ids (long long short); connectors	(□ long □ short)
DOM position 14	DOM id: TP6H 7519
(T, Long) Cable mark: 758	<u> </u>
Bottom shackle connected Top clutch connected at link #/9 Bow OK → □ clutch zip tied Photos: ✓ phi orientation □ whole view	Δ(14-15):(¬, 0
DOM position 13	DOM id: UP 6 74236
(U, Short) Cable mark: 775	
☐ Bottom shackle connected ☐ Top clutch connected at link # ☐ Bow OK → ☐ clutch zip tied ☐ Photos: ☐ phi orientation ☐ whole view	Δ(13-14): 16.9
Breakout 7	Time:
	Now 1:49
- LongDOM	Now 1:49
☐ connector O-ring in place and ☐ lubed	Last b/o Δt [min]
breakout O-ring in place and lubed	Depth:
A connected	Paro 8 36
	Keller 835
- ShortDOM	Payout
connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	
Loose pigtails taped to cable	
e e e	
	e 🙃



DI DOME'I (m/I	in 1 N	
Photos: DOM ids (18)	ong 🛮 short); connectors	
DOM position 12		DOM id: TP <u>6 Y4355</u>
(T, Long) C	able mark: 792	
Bottom shackle con Top clutch connecte Bow OK → ☐ clutch Photos: ☐ phi orientat	ed at link # <u> </u>	Δ(12-13): 17-0
DOM position 11		DOM id: UP 6 Y4480
in the second se	able mark: 🔫 🛭 🤊	DOM 10. 01
Bottom shackle con	nected ed at link #(^) ch zip tied	Δ(11-12): 6.9
Breakout 6		Time:
Dieakout o		
8		Now_ /: 55
- LongDOM	2 2	Last b/o
	g in place and □ lubed	Δt [min]
_	in place and □ lubed	Depth:
connected ×		Paro 870
Cla costDOM		Keller 870
	g in place and □ lubed in place and □ lubed	Payout694
Loose pigtails taped	l to cable	
Α		
20		
	☐ All clear to lower cab	ole ©



A A A A A A A A A A A A A A A A A A A		
Photos: DOM ids (☐ long ☐ short); connectors (☐ long ☐ short)		
DOM position 10		DOM id: TP 5 # 0 1 95
(T, Long)	Cable mark: 726	
\bowtie Bow OK $\rightarrow \Box$ cl	ected at link #	Δ(10-11): 17.0
DOM position 9 (U, Short)	Cable mark: coverdin +	DOM id: UP 6 7.4476
Bow OK → ★ cl	ected at link #(7	Δ(9-10): 16-9
Breakout 5		Time:
		Now 2:04
- LongDOM		Last b/o
	ring in place and □ lubed	Δt [min]
onnected	ng in place and □ lubed	Depth: * Paro ♀ 🌣
Acomected		Keller 905
- ShortDOM		Payout -722
	ring in place and □ lubed ng in place and □ lubed	· · · · · · · · · · · · · · · · · · ·
(Loose pigtails tap	ped to cable	y H
		2 A 1
All clear to lower cable ☺		



Photos: DOM ids (☆ long ⋈ short); connectors (□ long □ short)		
DOM position 8	DOM id: TP 6 Y 4409	
(T, Long) Cable mark: 859,5	A	
Bottom shackle connected Top clutch connected at link # / 1 Bow OK → ★ clutch zip tied Photos: phi orientation ★ whole view	Δ(8-9):_/7,0	
DOM position 7	DOM id: UP 6 /4300	
(U, Short) Cable mark: taped over	n	
Bottom shackle connected Top clutch connected at link #(9 Bow OK → M clutch zip tied Photos: A phi orientation M whole view	Δ(7-8):	
Breakout 4 broken, no tape) See that	Time:	
See (noto	Now 7 10	
- LongDOM	Now 2!/2 Last b/o	
© Connector O-ring in place and □ lubed	Δt [min]	
☐ breakout O-ring in place and ☐ lubed	Depth:	
⊠ connected	Paro 9 39	
	Keller 939	
- ShortDOM	Payout -751	
☐ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☐ connected☐		
Loose pigtails taped to cable	•	
Loose piguins taped to easie		
* ************************************	2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2	
☑ All clear to lower cab	le 😡	

slow down while drillers = Red, Dave, Jim gone

Photos: DOM ids (long ☐ short); connectors (☐ long ☐ short)		
DOM position 6		DOM id: TP GH 7511
(T, Long)	Cable mark: 89 3.5	8
Bow OK → X clu	cted at link #(9	Δ(6-7): (7.0
DOM position 5		DOM id: UP 6 Y 432L
(U, Short)	Cable mark: 910.5	
Bottom shackle come Top clutch connect Bow OK → △ clu Photos: △ phi orient	cted at link # 19	Δ(5-6): 16.9
Breakout 3		Time:
		Now 2:28
- LongDOM		Last b/o
	ring in place and □ lubed	Δt [min]
	ng in place and □ lubed -	Depth: Paro タラ <i>ソ</i>
onnected z		Keller 975
- ShortDOM		Payout -778
	ring in place and M lubed	
	ng in place and ☐ lubed	
connected		
Loose pigtails tap	ed to cable	1471 load
v =		<u>.</u>

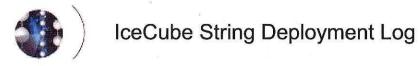
☐ All clear to lower cable ☺



Photos: DOM ids (long) sh	ort); connectors (\square long \square short)
DOM position 4	DOM id: TP 6 Y4765
(T, Long) Cable mar	k: 800 927.5
 Bottom shackle connected Top clutch connected at link Bow OK → A clutch zip tie Photos: A phi orientation □ w 	d
DOM position 3	DOM id: UP 674260
(U, Short) Cable mar	
(O, Onorty Cable mar	
☑ Bottom shackle connected	
Top clutch connected at link	# <u>18</u> Δ(3-4): 17.0
Bow OK → to clutch zip tied	\mathbf{d}
Photos: phi orientation M w	hole view
bow	2 27
Breakout 2 measure 2.40 -	Time:
ment	Now 2:44
ADDR. MATERIAL MATERI	, i
- LongDOM	Last b/o
☒ connector O-ring in place☐ breakout O-ring in place	
✓ connected	and □ lubed Depth: Paro 100 €
~ connected	Keller 1009
- ShortDOM	
© connector O-ring in place	Payout _ 800_
☐ breakout O-ring in place	
connected	and 1 labed
) Li Comicetta	
X Loose pigtails taped to cable	
И	
orașe _ roso s	
All clea	ar to lower cable ☺



Photos: DOM ids (Ž long ☒ short); connectors (☐ long ☐ short)		
DOM position 2	DOM id: TP 5 HO229	
(T, Long) Cable mark: 961.5		
B.D.4411		
Bottom shackle connected	16.9	
☐ Top clutch connected at link # ☐ Bow OK → ☑ clutch zip tied	Δ(2-3): 16.9	
Photos: A phi orientation A whole view	v	
(bow=2.43 - 2.40)		
DOM position 1	DOM id: UP 5-H0224	
(U, Short) Cable mark: 978	200	
Bottom shackle connected		
Top clutch connected at link #(8	Δ(1-2): 17-0	
Bow OK → Clutch zip tied		
Photos: phi orientation whole view		
Breakout 1	Time:	
Breakout i	rime.	
	Now 2:5 2	
- LongDOM	Last b/o	
Connector O-ring in place and □ lubed	Δt [min]	
□ breakout O-ring in place and □ lubed	Depth:	
X connected	Paro 1642	
CI IDOM	Keller 1042	
- ShortDOM	Payout _ 823.}	
✓ connected		
Connected		
Loose pigtails taped to cable	•	
No second Paro no more	8	
No. 5		
☐ Group photo		
☐ All clear to lower cable		



Uphole Pressure Sensor (Setra)

After DOM1 is safely under the surface (> 50 m)

	Time:
☐ Stop the cable winch	
☐ Lower Setra pressure sensor into hole	
☐ Distance to Setra from floor:	1
☐ Setra readout verified with monitoring s	system
□ Well depth from Setra:	
☐ Well depth from laser:	
If the two well depth measurements agree:	:
☐ Switch to Setra well depth in monitoring	g system
	Time:

Now the String Drop begins



# 								
(See	back of	prev. Stri	ng Drop	•			
,	Se back of prev. String Drop Page for AVRA notes The target depth is 2450 m							
= 250)	f (1	deployment	on their o	wa eable da	ped to Iac	be		
m	- Swite	ch cable win	ch to computer	control	Per d	3 load	61	
	NCA COSTO						F , 22)	
			Time: 3:15 Time: 3:25			1500		
			Time: 3:44			1833		
			Time: 3:54			9		
	Speci	d. 711	Time: 4:09	Depth: 74	30			
			Time:	Depth: 27	<u> </u>	54		
	= Spee.	1 S			d succ all	.F Pro	- 50	
	Depth Monitoring (log on the fly - do not stop for this) = 5							
	Depth by	Time		Depth by	Depth by	Δdepth	= (4)	
2	Paro ¹	ııııé	Well depth ¹	cable marks ²	355	P-K¹		
123 124	1000 m	3:06	51.2	1057.4+21.4	- (something)	~-1	5.4	
reh	1500 m	3:27	oder 50.2	-1078.81	_ 1284.9	- 2.7	8.4	
owell	1997. X	3:58	48.8	1964.8-11.4	fuched	-3.9	12.	
84.2	2100 m	8 4:16	48.2	= 1986 21 2154.0+21.4	G	-5.3	14.	
ith /	2200 m	6:00 pm	45.8	= 2 175.4 2 = 60.1 +21.4	t _t	-6.0	15.	
ven (6:14 pm	45.3	2361. 7 421.4	N .		16.9	
	2400 m		H903	= 23 83.1			ng sa	
	¹Read off n	nonitoring scre	een (at DO)	MEO) 17	-21 4	DOM(0)		
Lare 1	² Cable mar	(fre	(at DO.	[M159] - 1/m =	(at)	DOM60)		
		(III)	(3	058->-4	c 59	v		
Fter	∃ Switc	th to manual	cen (at DO) om p.4) control @ 240	$00 \text{ m} \rightarrow -2$	1060,1	-21.41		
AURA	■ Well	depth			vsing	a cd val 460-	59]	
	(a), 2	420:				-17.9		
	_	440:				v		
	Positi	on string at	target depth of	2450 m	Time:	6:25		
	★ String secured with Yale grip and anchor chain Time: 6:3							



Absolute	depth	with b	oottom	Paro
(depth in m	ieters a	nd pre	essure i	n PSI)

☐ Distance from Paro to DOM60:			
$d_{Paro-DOM59} = \underline{\qquad} (from p. 4)$			
$d_{Paro-DOM60} = (d_{Paro-DOM59} + 17) m =$	← insert below		
☐ Convert Paro pressure to string depth:	,		

$$K = 3.78151 \cdot 10^{-6}$$
 /PSI (compressibility of aerated water)

(use 6 decimals for exp's)

Ambient pressure (from p. 4):
$$P_0 =$$
_____PSI $\rightarrow \exp(-KP_0) =$ _____

Subtract exponentials
$$\rightarrow$$
 = ________

Paro depth in water
$$\rightarrow$$
 = m

Add distance to DOM60 (above)
$$\rightarrow$$
 + _____ m

Add well depth
$$\rightarrow$$
 + ____ m

Depth of bottom DOM
$$\rightarrow$$
 = ____ m

Final depth estimates

◄----- read off deployment screen ------

Time:	Paro		Keller		*Payout*		Cable marks	
Reading	3429.04	PSI	2691.0	PSI		m	2413 4	m
Offset	9.79	PSI	-4-19	PSI	X	m	21.4	m
Well depth 44.5			m final					
Dist. to DOM60 m			m	This space is intentionally left blank				
DEPTH (DOM60)	2452.3		2460.0		0	1	2434.4	ä

Time: 6:43 pm

of mitch

Final depth (DOM60): 12 45 2.3 m



Deployment Closeout
Log entries complete
String safely secured
Hole covered and secured
Equipment safely shutdown and secured
Deployment data OK (in database)
X Site cleanup
Deployment crew dismissed
String deployment complete
Time: 6:46 pm Date: 1/20/07
Shift Lead:
name / signature
PTS Lead:
Deployment Manager: name / signature
Safety Officer:
IceCube On-ice Lead: Albrech lebele name / signature

IceCube Deployment Monitoring Check Sheet (IDMCS)

Version 4.0 December 12, 2006

Kurt Woschnagg, UCB

General instructions

- ► Read through this entire document before deployment starts.
- ▶ Deployment monitoring is done with a computer (housed in the TOS) running drill/deployment monitoring software (by Chuck Rentmeesters) with a GUI for readout and manual inputs. All deployment sensor data and manual inputs are logged and saved on disk by this system.
- ► For each manual entry into the monitoring interface (marked **ENTER** below), also make a note in the logbook (marked *Logbook* below).
- For each entry in the logbook, include time and name (initials).
- ▶ Write down as much useful information you can think of (it will all be needed sooner or later).

Measurement instructions

- ▶ All vertical measurements are relative to the floor of the tower (not the lip of the kick board).
 - Measure well depth from this level.
 - Take cable mark readings at this level.
- ➤ The location of a DOM on a string (for distance measurements) is defined as the position of the center of the sphere (at the equator defined by the harness).
- ▶ When taking a cable mark reading, estimate the location to nearest cm (0.01 m) with closest cable marks and tape measure.
- ► The location of a Paro is defined at the bottom of its body (at the little hole with the nipple).
- ▶ The location of a Keller is defined at the row of holes in the black plastic nose cap.
- ▶ The distance between a pressure sensor and the nearest DOM is positive/negative if the unit is above/below the DOM.
- ▶ Well depth is measured with a laser ranger (if possible), or with a tape measure (if not).
- ► The unit used for all distances and depths during deployment is **meters**.

Screen Tab: TOS ▶ Deployment

▶ Sensors/Graph

This is the main tab used during deployment monitoring. No input required on this tab.

Pressure/Depth of String Current and ambient (air) pressures, and the corrected depths at DOM60.

Spacing/Depth Comparison Difference in depth from pressure data. Should be stable during deployment!

Velocity

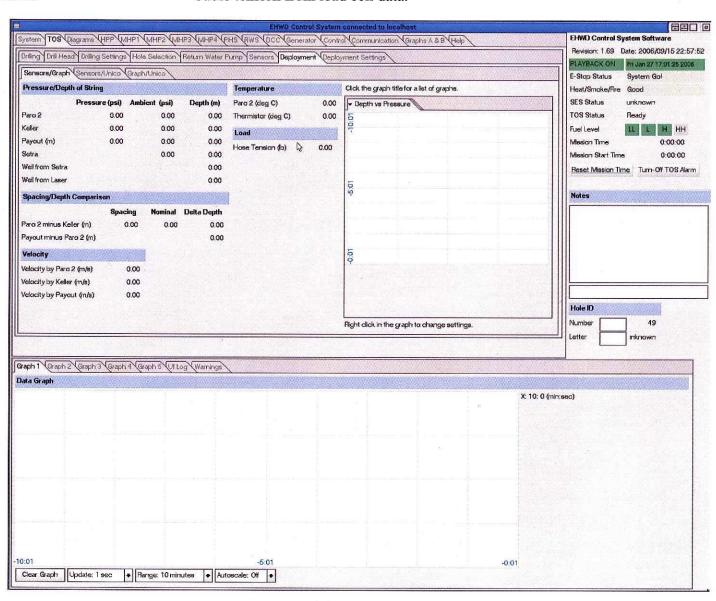
The deployment velocity calculated from recent pressure/payout readings.

Temperature

Temperature readings.

Load

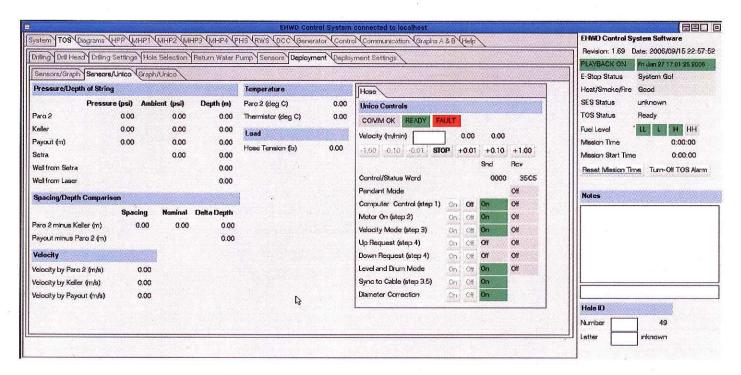
Cable tension from load cell data.



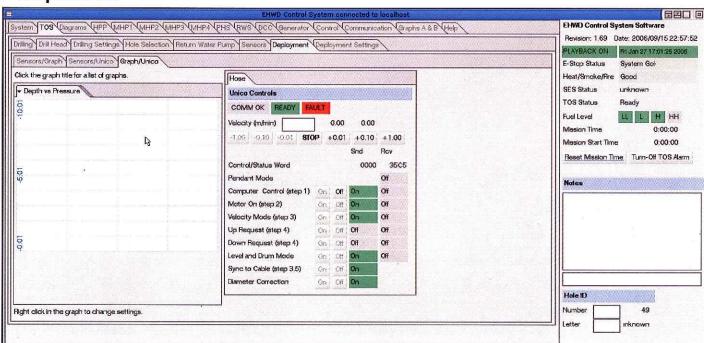
Screen Tab: TOS ▶ Deployment

▶ Sensors/Unico

This tab has the same data display as the main Sensors/Graph tab above, but instead of the graph window this tab has the controls for the Unico drive which controls the winch.



▶ Graph/Unico



Screen Tab: TOS ▶ Deployment Settings

▶ Settings

This is the main tab for entering information that is needed for a correct depth calibration of the pressure data. Make sure you understand what all the entries mean before deployment starts.

Tower Mode

Click on "Deployment".

Deployment Events

Click the appropriate button when one of the predefined events occurs (see list below).

DDB Mode

Select the correct DDB ID before deployment startup (needed for Keller calibration).

Payout at Tower

Reset payout when bottom DOM is at tower floor level.

Ambient Dressures

Well Depth Selection Select source of well depth used in depth calculation.

Ambient Pressures

Press "Get" when pressure sensor is attached to cable, or enter reading at that time.

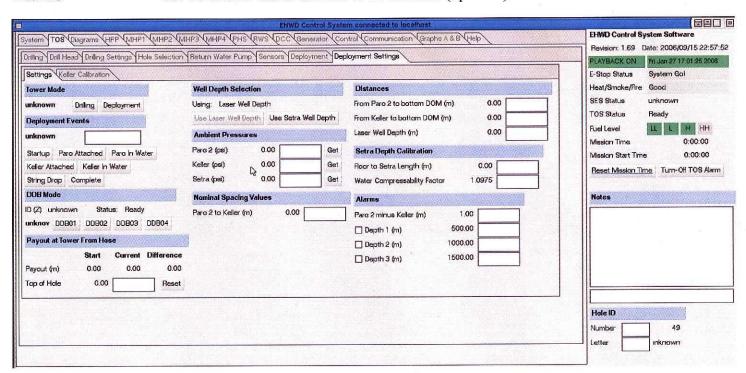
Nominal Spacing

Enter calculated distance between Paro and Keller.

Distances Setra Depth Calib. Enter calculated distances between Paro/Keller and DOM60, and well depth. Enter measured length of Setra cable, from floor to sensor.

Alarms

Set values for which alarm is to be sounded (optional).



Deployment Events

☐ Startup Click when the deployment begins.

☐ Paro Attached Click when the Paro is attached to the breakout and starts sending data.

☐ Paro In Water

Click when the Paro reaches the water.

☐ Keller Attached

Click when the Keller is attached to the breakout and starts sending data.

☐ Keller In Water

Click when the Keller reaches the water.

 \square String Drop

Click when the String Drop phase begins, after all DOMs have been attached.

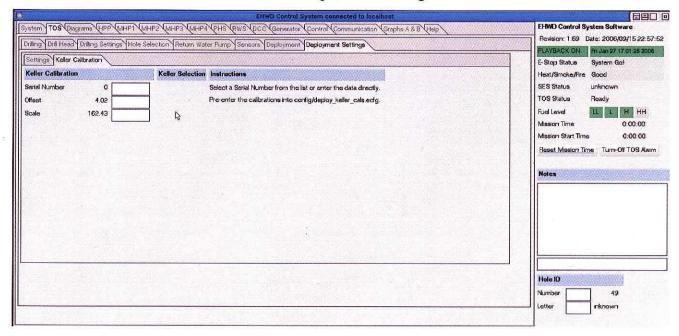
☐ Complete

Click when the deployment ends (string is secured, etc).

Screen Tab: TOS ▶ Deployment Settings

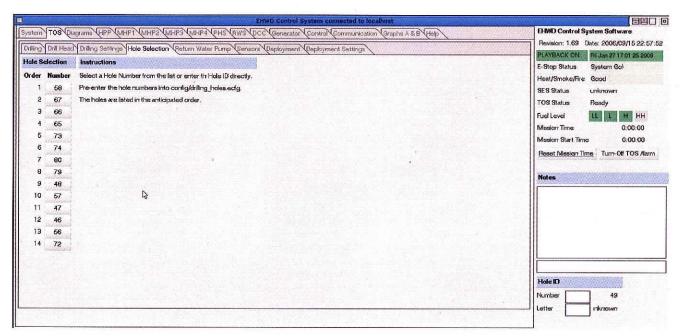
▶ Keller Calibration

On this tab you select the Keller ID by clicking on the appropriate button. The correct (pre-programmed) calibration constants will then be used for the Keller pressure reading.



Screen Tab: TOS ▶ Hole Selection

On this tab you select the hole/string number, *either* by clicking on the numbered button on the left *or* by entering it in the "Hole ID" field in the lower right hand corner.



Distances between devices

calculate manually and enter on Deployment Settings tab

Distance between Paro and DOM60:

Distance between Keller and DOM60:

$$\frac{1.7 \pm 0.29}{\text{plus 31.17 22}} = \frac{528.7}{529.1}$$

$$\pm 0.4 \pm 59 \pm 0.60 \text{ is}$$

Distance between Paro and Keller:

Notes:

There are 60 DOMs on every string.

The nominal spacing between DOMs is 17 m.

The nominal spacing between breakouts is 34 m.

Breakouts (1-30) and DOMs (1-60) are counted from the top.

The Keller is at breakout 15, just above DOM29.

The Paro is at breakout 30, just above DOM59.

(Fun Fact: There used to be a second Paro at breakout 1 on the first four strings)

Pressure conversions

		PSI	mH ₂ O	Atm
1 PSI	-	1	0.70	0.07
1 mH ₂ O	=	1.4	1	0.1
1 atm	=	14.7	10.3	1

Check Sheet

STRING # 57

DATE: 7:20

Before Deployment

- Action: Locate laser ranger for well depth measurements.
- Action: Locate metric tape measure.
- Action: Locate one Paro and one Keller, *plus spares* of each.
- Action: Locate bucket (for cooling of Keller sensor with water/ice mix).
- **Action**: Fill bucket with snow and place in heated area to make slush.
- Action: Locate Setra uphole pressure assembly (sensor + cable).

Deployment Startup

- Action: Click "Deployment" button under "Tower Mode" on Deployment Settings tab.
- Action: Select string (=hole) number on Hole Selection tab.
- Action: Note deployment start time. est arded soft ware 7:57

 Logbook: Time
- Action: Click "Reset Mission Time" on the right panel on the deployment screen.
- Action: Click "Startup" under Deployment Events.



IceCube String Deployment Monitoring

Action: Note DDB id number (1, 2, 3, or 4).

ENTER: DDB# (select button)

Logbook: DDB#

Action: Take a well depth measurement with the laser ranger.

Driller's estimate 9° m. This is the whee the drill has sprun a lank they lost lot water. Using 90 m, will try to im prove from cate man

ENTER: Well depth [m]

Logbook: Well depth

Action: Reset Payout when DOM60 breaks the plane of the floor. be muse of 17m extension

CLICK: "Reset" button (Top of Hole Reset) on Deployment Settings ▶ Settings tab.

Logbook: Payout Start value

X

Action: Get cable mark reading at DOM59.

Logbook: Cable mark [m]

4

Action: Attach Paro at breakout #30. (This is called "Paro2" on the monitoring screen).

Logbook: Paro serial number

A

Action: Click "Paro Attached" under Deployment Events.

Action: Measure distance between Paro location and nearest DOM.

Estimate distance to *bottom* DOM by adding *n* 17-meter segments (n should be 1 for the Paro since nearest DOM is #59).

ENTER: Distance [m] from Paro to bottom DOM (#60)

Logbook: Distance to nearest DOM, nearest DOM#, estimated distance to DOM60

Action: Get cable mark reading at Paro.

Logbook: Cable mark [m]

missed but measured to DOM 59



IceCube String Deployment Monitoring

X

Action: Take Paro air pressure reading just before it breaks the water surface.

ENTER: Ambient pressure [PSI] for Paro

Logbook: Paro2 air pressure

During Deployment

X

Action: Click "Paro In Water" under Deployment Events.

5

Action: Measure curved distance of main cable going around DOM (for at least two DOMs).

Logbook: Straight (vertical) distance for DOM segment, curved cable distance

X

Action: Measure real distance between neighboring DOMs (for every pair) with laser ranger.

Logbook: DOM#'s, distance

R

Action: Put Keller (and one spare) in bucket of water (at near freezing temperature) at least one hour before breakout #15 is reached.

Note: The Keller is not temperature corrected and must therefore be brought to the temperature of the water in the hole (0-2°C) before the air pressure offset is determined.

A

Action: Attach Keller at breakout #15.

ENTER: Keller serial number

Logbook: Keller serial number

K

Action: Click "Keller Attached" under Deployment Events.

X

Action: Measure distance between Keller and nearest DOM.

1.7 m

Estimate distance to *bottom* DOM by adding n 17-meter segments (n should be 31 for Keller since nearest DOM is #29).

ENTER: Distance [m] from Keller to bottom DOM (#60)

Logbook: Distance to nearest DOM, nearest DOM#, estimated distance to DOM60



IceCube String Deployment Monitoring

	Action: Get cable mark reading at Keller.
	Logbook: Cable mark [m] for Keller
	Action: Determine Keller air pressure offset before (or just as) Keller hits water.
	ENTER: Ambient pressure [PSI] for Keller
	Logbook: Ambient Keller pressure
X	Action: Click "Keller In Water" under Deployment Events.
X	Action: Get cable mark reading at top DOM. (640 to 1/20
	Logbook: Cable mark [m]
X	Action: Measure well depth as soon as top DOM is under water.
	ENTER: Well depth [m]
	Logbook: Well depth [m], measurement method (laser/tape)
19	Detroop DOM attachment and String Duan
	Between DOM attachment and String Drop
<u> </u>	Action: Lower Setra assembly into hole (after top DOM is at least 50 m under the surface).
	Action: Measure distance between Setra sensor and floor of tower (distance marked on cable).
	ENTER: Distance Setra to floor [m]
	Logbook: Distance Setra to floor
	Action: Measure well depth with Setra system and laser ranger and compare.
	Logbook: Well depth from Setra [m], well depth from laser [m]
	Action: If the two well depth meaurements agree, switch from laser to Setra in monitoring system.

During String Drop



Action: Click "String Drop" under Deployment Events.



Action: Measure well depth manually (with laser ranger and/or tape measure).

(if shift lead allows: repeat several times during drop)

ENTER: Well depth [m]

Logbook: Well depth, measurement method (laser/tape)



Action: Read cable marks at regular intervals.

Logbook: Cable mark [m]; depth readings [m] (Paro, Keller); time

End of Deployment

Action: Get final pressure readings from Paro and Keller when final depth has been reached.

Logbook: Pressure readings [PSI]; corrected depths [m] (from screen)

Action: Get final well depth reading (laser and/or Setra).

HAS TO BE SIMULTANEOUS WITH FINAL PRESSURE READINGS!

Logbook: Well depth [m] (laser); well depth [m] (Setra)

Action: Note deployment end time.

Logbook: Time

Action: Click "Complete" under Deployment Events.

DOM List for String #57 (10)

Name	DOM ID	<u>Position</u>
Golden_Bell	TP6P1227	60
Stadion	UP5H0200	59
Tippen	AP5H0237	58?
Svan	UP5H0130	57
Janaka	TP6Y4281	56
Finnkobben	UP5H0226	55
Storkrake	AP5H0221	54
Enkelbeckasin	UP5H0136	53
Guandi	TP6Y4477	52
		52
Tottby	UP5H0212	50
Sommargylling	AP5H0217	
Bagarmossen	UP5H0182	49
Orischa	TP6Y4309	48
Baldersgatan	UP6H7512	47
Struts	AP5H0205	46
Fridhemsplan	UP5H0208	45
Pembele	TP6Y4243	44
Sickla	UP5H0246	43
Lira	TP5H0153	42
Ripa	UP5H0152	41
Nyama	TP6Y4237	40
Roskari	UP5H0126	39
Kaja	TP5H0105	38
Vaktel	UP5H0194	37
Kek	TP6Y4421	36
Husby	UP5H0114	35
Mafdet	TP6Y4251	34
	UP6P1262	33
	TP6P1477	32
Chnubis	UP6Y4232	31
Tecciztecat	TP6Y4349	30
Нар	UP6Y4424	29
Canobus	TP6Y4401	28
Odudua	UP6Y4244	27
Bastugatan	TP6H7515	26
Bes	UP6Y4396	25
Fasan	TP5H0103	24
1 43411	UP61206	23
Stork	TP5H0129	23
Stork		21
Kadru	UP6Y4416	
Manezet	TP6Y4271	20
Maat	UP6Y4284	19
Thorildsplan	TP5H0185	18
Mesektet	UP6Y4422	17



String Installation Traveler

Surface Cable#: Length (m):	57 514 m	Start date:	05-06 sason
Surface to DOM	Cable#: 34	Start date:	1/22/2007

V	Process Step	Doc. no.	Tech initials	Date Completed	Comments				
1	Visual Inspection of Cables at Pole	9400- 0006-QLP	M	1/22/07	A	H H			
	Surface Cable Assembly Inspection Pass Fail By: Surface to DOM Cable Assembly Inspection Pass Fail By: MC								
2	Trench Surface Cable Assembly (SCA)	9400- 0006-QLP	MC	8	05-06 slason	- B-5-03			
3	Install SCA into Surface Junction Box (SJB)	9400- 0006-QLP	MC		05-06 slason	(
4	Install SCA into ICL	9400- 0075-PLN			п				
5	Complete IceTop FCU Power and Data Installation Procedure	9400-005- QLP	57						
6	Verify Connectivity of IceTop DOMs with Quad Connectivity Tester (QCT)		MK	1/15/07	2				
7	Pre-deployment Inspection Procedure		MC	1/22/07					
8	S2D Cable into SJB installation	9400- 0007-QLP	MK	1/25/07	=				
9	Wet Connector Testing of Quads	Z V	M	1/25/07	8 °				
10	QCT Testing of Quads		MK	1/25/07	3				
11	SJB Final Inspection Complete (Ok to Bury)	9400- 0007-FRM	MC	1/26/07	-				
12	Handoff to IceCube C &V Team		M	1/24/27					



ITQ2

String Installation Traveler

String QCT and Wet Connector Test Form

String # 57	Name of Tester: Mike Kleis	1
	. ()	

QCT Results

	# o1	f DOMs (0	, 1, 2)	Wet Con	nector Tes	t Results	(micro Amps)		
Quad name	# of DOMs WP0	# of DOMs WP1	Pass/ Fail	J	L, o o	M	K	Pass/ Fail	Recheck Pass/ Fail
Q2	7	9	P			8	187	P	
Q3	7	3	P	30	= =		9	P	
Q4	7	2	8		4			P	
Q5	2	2	P					P	N N
Q6	2	2	3				9	P	9.
Q7	7	2	P					P	
Q8	2		P		4			P	
Q9	2	3	P				7.	Ø.	
Q10	2	2	P		14			9	
Q11	2	2	P	. 19				P	
<u>ي</u> 12	2	2	9					8	
Q13	2	2	P					P	
Q14	2	2	P					B	
Q15	2	2	P					8	
Q16	9	2	P					P	
IceTop Quads		54							
ITQ1	l l	1		*	10		۸		
									-

Service Quads	Device Connected	Verified on	Tech Initials	Comments
Q1	0 ,			
Q17	"			v /
Q18	a a	п		и 8
Q19				
<u>2</u> 20	8			*